



# ENGINEERING DESIGN PROCESS

FRC Team 1640 Sab-BOT-age



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- 5 Years involved in FRC
  - ▣ Student – Team 1902, 2614
  - ▣ Mentor – Team 1640 (2012-present)
- Mechanical Engineering Student – Delaware County Community College



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- 5 years in FRC (8 years in FIRST)
  - Student – Team 1640 (2010-2012, Co-captain & Driver 2012)
  - Mentor – Team 1640 (2012-present)
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# Engineering Design Process

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- What is it?
  - ▣ Design new products
  - ▣ Iterate existing products
    - Make them better
  - ▣ Design systems
    - Large scale – manufacturing systems
    - Small scale – product subsystem



# Engineering Design Process

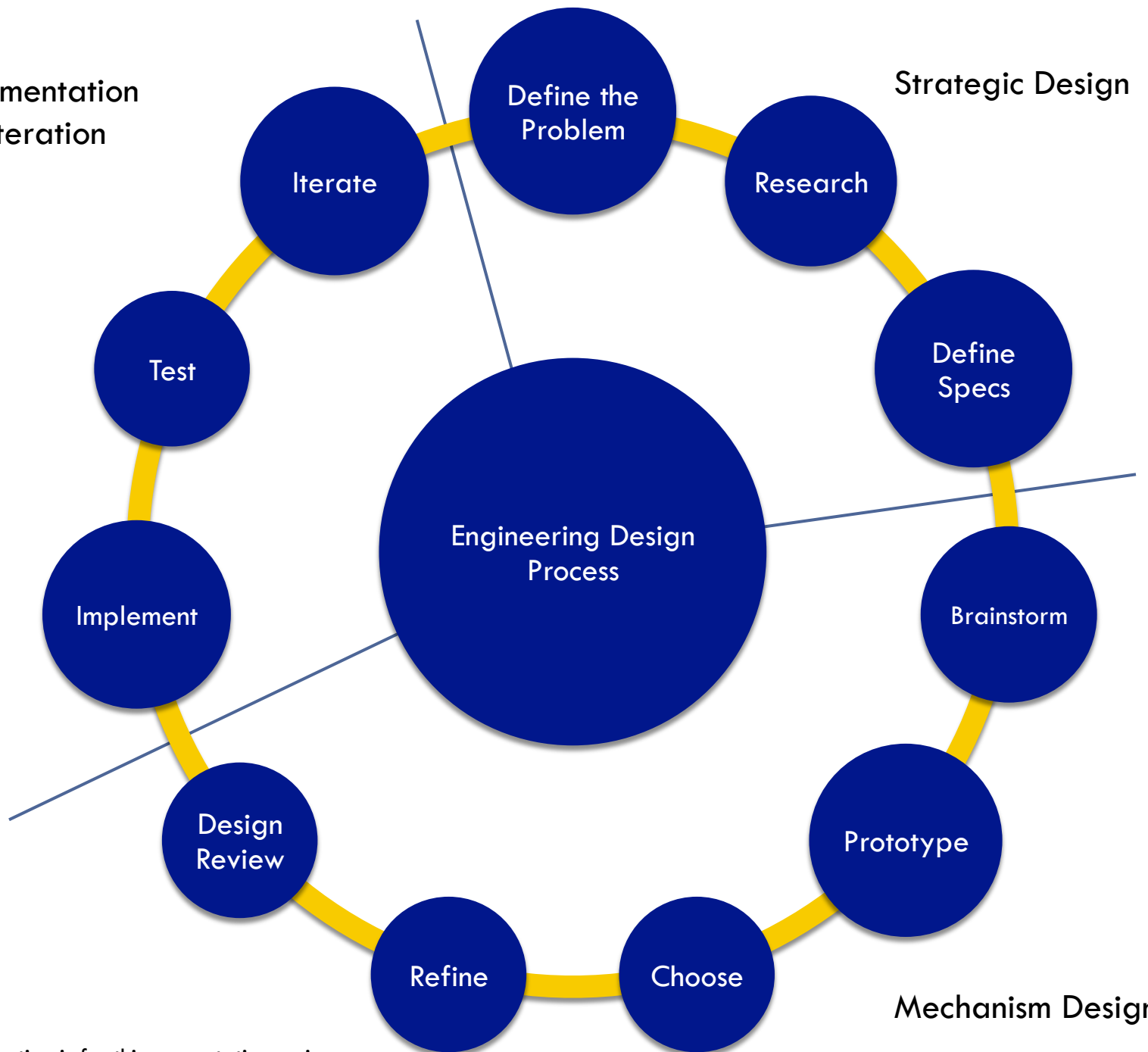
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- How does this apply to FIRST?
  - ▣ IT'S WHAT WE DO!
  - ▣ We use this process to design our robots and all of its' subsystems
  - ▣ Also award entries, business strategies, training, etc.
- Circular, non-linear process
  - ▣ Return to any point during the process
- So, what exactly is it?
  - ▣ Varies industry-to-industry, but the fundamentals are the same



Implementation  
and Iteration

Strategic Design





# Define the Problem

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- Beginning of Strategic Design
  - ▣ Define what you need to accomplish
  - ▣ What are this year's objectives? Rules? Penalties?
- The objective is to UNDERSTAND the game inside and out and to determine possible game strategies
- For a more in-depth description of Strategic Design, please watch:
  - ▣ <https://www.youtube.com/watch?v=4ysSvxR-tAs><sup>1</sup>
  - ▣ <https://www.youtube.com/watch?v=smWy7FQ8jLE><sup>2</sup>

1: Kanagasabapathy, K. (Director). (2014, October 8). *Simbot Seminar Series - Strategic Design* [Video]. Youtube.

2: FIRST. (Producer), & Kanagasabapathy, K. (Director). (2013, November 6). *FRC Ask an Expert: Effective FIRST Strategies with Karthik* [Video]. Youtube.



# Define the Problem

- Create a Scoring Model
  - ▣ Define ALL tasks/actions
  - ▣ Define value for accomplishing tasks/actions
    - Some tasks/actions might not have a point value, but do have a time value
  - ▣ Define probability of completion for each task/action

Inputs	Seconds to Completion	Probability of Completion	Point Value	Cumulative Probability	Expected Value	Tele-Op Time (Sec)
Time to Score High	10	75%	10	75%	7.5	140
Time to Hurdle	8	100%	10	100%	10	
First Assist	10	80%	10	60%	6	
Second Assist	10	75%	20	45%	9	
Ball Return Time	10	100%	0	100%	0	
Catch	15	10%	10	10%	1	
Resulting Teleop Scores	Best Case Score	P(Best Case)	Expected Value			
One Robot Scoring	70.00	75%	52.50	Bad		
One Robot Hurdle & Score	100.00	75%	87.50	Great		
One Assist, Score	93.33	60%	63.00	Bad		
One Assist, Hurdle & Score	110.53	60%	86.58	Great		
One Assist, Hurdle, Catch & Score	105.66	6%	64.72	Bad		
Two Assist, Score	140.00	45%	78.75	Okay		
Two Assist, Hurdle & Score	145.83	45%	94.79	Great		
Two Assist, Hurdle, Catch & Score	133.33	5%	74.44	Okay		





# Define the Problem

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- Develop game strategies
  - ▣ Decide on a game strategy utilizing your scoring models and determine all possible game strategies
  - ▣ LET THIS STRATEGY GUIDE YOUR DESIGN!!!
    - Don't let your design dictate your strategy!
  - ▣ What happens when your strategy has to play with other strategies? With the same strategy? Against your strategy? Against other strategies?



# Research

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- See what has been done in the past to accomplish this task
- FIRST games may share similarities with previous games
  - Aerial Assist (2014), Breakaway (2010) & Overdrive (2008)
  - Ultimate Ascent (2013), Rebound Rumble (2012), Aim High (2006) & FIRST Frenzy (2004)
  - Logomotion (2011), Rack 'N' Roll (2007) & Triple Play (2005)



# Research

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- Look in industry to find inspiration
- Look on the web
  - ▣ Chief Delphi
  - ▣ FRC Designs
  - ▣ The Blue Alliance
  - ▣ VEX/FTC
  - ▣ Google



# Define Specifications

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- This is where we start to define WHAT we want to do
- Two types of specifications:
  - ▣ Design Constraints
    - Specifications that the robot MUST follow
      - Max height; Max weight; # of motors; follow all rules; must be manufacturable; Can't reach # outside from robot; Is within budget; etc.
  - ▣ Functional Requirements
    - What the team believes the robot should be able to do
      - Hold # of game pieces; Mechanism can lift # tall; Mechanism is # fast; etc.
    - Expand these requirements with what you *Wish*, *Prefer*, and *Demand* the robot be able to do



# Brainstorm

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- Moving into Mechanism Design (separate PowerPoint will elaborate on these parts of the process)
- Begin to determine HOW to accomplish specs and perform strategy
- Napkin Sketches
- Utilize your research



# Prototype

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- Create some of the concepts from brainstorm
- Collect data from the prototypes under real-world conditions
  - ▣ Doesn't matter if it can hold 1000 of a game piece if it can't score them in the allotted game period
- Begin to utilize CAD if necessary
  - ▣ Makes choosing/designing the final product easier in the long run
- Try to see if your specs will work or need tweaking
- Try to find any critical components to the design
- DON'T MAKE THE PROTOTYPES "Yours"; they're the team's prototypes
- Record all successes and failures and iterate the prototypes



# Choose

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- Can't prototype forever
- Need to pick a direction
- How?
  - Put prototypes against each other using **QUANTITATIVE** data
  - Do they meet the specifications? How well do they meet them? Can they meet them better?
  - Weighted-Objectives Table
- **DON'T PERSONALIZE** the designs!



# Weighted-Objectives Table

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- Use specifications
  - ▣ Add weight to specs based on importance to strategy/team
- Give the prototypes a value for each specification
  - ▣ Based on the quantitative data
- Multiply these values by the weight and sum the resulting values

	Weight	Slingshot		Catapult (Elastic) (Low)		Catapult (Elastic) (High)		Catapult (Motor)		Linear Launcher / Roller Claw	
		Score	Weighted Score	Score	Weighted Score	Score	Weighted Score	Score	Weighted Score	Score	Weighted Score
Complexity (Higher is less complex)	5	8	40	7	35	8	40	8	40	4	20
Range (Allowing Driver Error)	5	4	20	6	30	10	50	7	35	10	50
Safety	15	9	135	4	60	4	60	8	120	6	90
Autonomous	10	3	30	8	80	9	90	5	50	8	80
Space	2	4	8	4	8	3	6	3	6	1	2
Ball Containment	10	9	90	5	50	7	70	6	60	10	100
Weight	3	8	24	8	24	6	18	5	15	2	6
Height	10	9	90	4	40	9	90	4	40	2	20
<b>Total</b>	<b>60</b>	<b>54</b>	<b>437</b>	<b>46</b>	<b>327</b>	<b>56</b>	<b>424</b>	<b>46</b>	<b>366</b>	<b>43</b>	<b>368</b>





# Refine

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- Begin to design the final product
  - ▣ Utilize CAD!
  - ▣ Math and Physics!
  - ▣ Make sure you can make it!
- Determine design calculations
  - ▣ Someone might have done it before – see what you can find
  - ▣ Excel is your friend!



# Refine

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- When designing the final product, keep in mind:
  - ▣ Modular design
    - Quickly and easily replaceable parts
  - ▣ Interchangeable replaceable parts
    - No “left side” or “right side” parts
  - ▣ Robustness
    - FIRST is a contact sport
  - ▣ Serviceability
    - If parts need to be repaired on-robot, make sure hands and tools can get where they need to be
  - ▣ Don't go overboard with different sizes and types of hardware
    - Using only a few sizes and types of nuts, bolts, washers, etc. reduces the number of tools and spare hardware needed at competition



# Design Review

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- Review your design
  - ▣ Minimum: with student leads and mentor leads
  - ▣ Maximum: with entire team (can be too much)
  - ▣ Go over why design decisions were made
  - ▣ Address any potential design issues
  - ▣ Address potential critical design points
  - ▣ Does it meet the specs?



# Implement

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- Time to put everything together
- Systems integration
  - ▣ Put your robot together
  - ▣ See if any designs interfere with each other
    - Should have been done in CAD before, but might have missed it



# Test

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- MAKE SURE EVERYTHING WORKS
- If not, what can be done to make it work?
  - ▣ Does it really need to be completely redesigned?
  - ▣ Are you sure?
- Let it run under it's own power and it's own code (if ready)
- See if it meets the specifications and see if it can complete the strategy



# Iterate

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- Can it work better? More efficiently? Faster?
- Can it be lighter?
  - ▣ Is it possible to make it lighter?
- Does it meet all the specifications?
  - ▣ What can we do to make it meet the specs?
- Restart the process when/where necessary



# Some Notes

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- Don't make designs/prototypes personal
  - ▣ That makes choosing personal
- Use quantitative data when choosing
  - ▣ Don't pick a design because you "feel it'll work" or because you "want this design"
  - ▣ This and/or the first point will degrade the choosing process until it becomes a screaming match, which is NOT how a design is chosen
- Remember: GP applies all the time!



# Some Notes

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- Don't design something that you can't make
- Only given 6 weeks and 3 days!
- Make sure you can assemble the systems and put them on the robot
  - ▣ If parts need to be welded to the chassis, then that needs to be determined and conveyed ASAP
- Make sure parts can be repaired
  - ▣ Things break
  - ▣ Murphy's Law (Stuff happens at the worst possible moment)
- Try not to start brainstorming immediately after kickoff
  - ▣ Understand the game and define your strategy first





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Questions?



# Contact

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